Application of the I-Effective Method in Calculating Deflections of Partially Prestressed Members



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For computing curvatures and deflections of partially cracked members, the effective moment of intertia (I'_e, I_e) method^{1,2,3} provides a transition value between well-defined limits in the uncracked $(I_{uer} \text{ or } I_g)$ and fully cracked (I_{er}) states.

The method is applicable to shorttime deflections of non-prestressed and prestressed members alike, and empirically accounts for the effect of tension stiffening (increased stiffness due to concrete in tension, including between cracks). It is also applicable to individual sections, to simple beams, and between inflection points of continuous beams; so that a practical solution that takes into account the random distribution of cracks for all cases, including non-uniform members, is available. The method is similar to the approach^{4,5} of determining the partially cracked deflection as an intermediate value between the uncracked (State I) and fully cracked (State II) deflections.

The *I*-effective method has been adopted for the 1971 and 1977 ACI Building Codes,⁶ the 1971 and 1978 PCI Design Handbooks,⁷ the 1973 and 1977 AASHTO Highway Bridge Specifications,⁸ and the 1977 Canadian Building Code.⁹ However, its application to non-prestressed and prestressed members has been somewhat different in the past;³ with the live load I_e for prestressed members determined from the prestress plus dead load deflection point, as shown in Fig. 1, and not from the zero deflection point, as in the non-prestressed case using the dead

Synopsis

Unified *I*-effective procedures for partially cracked non-prestressed and prestressed member curvatures and deflections are summarized. Deflections computed by numerical integration of curvatures (using *I*[']_e in the fourth power equation), and also by direct calculation (using *I*_e in the third power equation) are illustrated for a typical single-T beam designed as a partially prestressed member in accordance with the ACI Code.

The numerical integration procedure readily lends itself to computer solution for both determinate and indeterminate structures. Results by the two methods are seen to be in close agreement.



Fig. 1. Moment versus deflection for a partially cracked prestressed member as previously computed by the *I*_e method.



Fig. 2. Basic stress distribution diagrams for uncracked, partially cracked and fully cracked prestressed members, with the location of the centroidal and neutral axes shown.





load plus live load I_e . The basic method has been shown to apply to first loading cases and to the envelope of repeated loading cases for at least 313 beams and slabs and 21 different authors.¹¹

In this paper, unified procedures for computing partially cracked non-prestressed and prestressed (with or without non-prestressed tension steel) member curvatures and deflections are summarized and illustrated by an example of a partially prestressed member designed in accordance with the ACI Code.⁶

The analytical and experimental development of these unified procedures is described in Refs. 10 and 11 in which the procedures were found to apply to load levels well beyond the usual service load range.





UNIFIED PROCEDURES FOR PARTIALLY CRACKED NON-PRESTRESSED AND PRESTRESSED MEMBER CURVATURES AND DEFLECTIONS

This case applies to the condition:

$$(M_D + M_L - P_e e_p > M'_{cr})$$

The basic stress distribution diagrams for uncracked, partially cracked and fully cracked members, with the location of the centroidal and neutral axes, are shown in Fig. 2 for a prestressed member. The partially cracked state includes empirically the effect of tensile concrete, including in small moment regions, from the top of each crack to the neutral axis, and also between cracks, referred to as tension stiffening.





In this procedure, which includes the effect of the normal force P_e in the calculation of the cracking moment, the fully cracked section is still taken in the limit to be the lower bound state, as shown in Fig. 2; that is, I_{cr} is the lower limit of I'_e and I_e for both non-prestressed and prestressed cases. The effect of any non-prestressed tension steel in prestressed members is included in the calculation of I_{cr} . As described in Refs. 10 and 11, the solution for non-prestressed members follows automatically in the unified procedure by simply setting the prestress force equal to zero.

For the general case of a member loaded into the cracking range, the strains and curvatures are shown in Fig. 3, and the idealized moment-curvature and moment-deflection curves are shown in Figs. 4 and 5.

Curvature at a Particular Section

From distribution line (1) in Fig. 3, the curvature due to prestress is given by Eq. (1) and shown in Fig. 4:

$$\phi_p' = P_e e_p / E_c I_g \tag{1}$$

In the case of statically indeterminate prestressed structures, $\phi'_p = M_{bv}/E_c I_g$, where $M_{bv} = M_{bv}^g + M_{bv}'$ includes both determinate and indeterminate moments due to prestress. Although the remainder of the development herein pertains to statically determinate cases, the procedures are equally applicable to indeterminate cases. The initial curvature due to the prestress force at transfer, P_i , is given by Eq. (2):

$$\phi_p = \phi'_p \left(E_c / E_{ci} \right) \left(P_i / P_e \right) \tag{2}$$

The dead load curvature is given by Eq. (3) at the time under investigation (shown in Fig. 4), and by Eq. (4) initially:

$$\phi_D' = M_D / E_C I_g \tag{3}$$

$$\phi_D = \phi_D' \left(E_c / E_{ci} \right) \tag{4}$$

Distribution line (2) in Fig. 3 corresponds to the condition of zero curvature, as shown in Fig. 4 and defined by Eqs. (5), (6) and (7).

From
$$M_D + M_{L1} - P_e e_p = 0$$
:
 $M_{L1} = P_e e_p - M_D$ (5)

and

$$\phi_{L1} = \phi_p' - \phi_D' \tag{6}$$

In this uncracked region:

$$\phi_{L1} = M_{L1} / E_c I_g \tag{7}$$

where M_{L1} is the part of the live load moment necessary to produce the zero curvature.

From distribution line (3) in Fig. 3, corresponding to first cracking, Eq. (8) is obtained. The cracking moment, M'_{cr} ,

is also shown in Fig. 4 and refers to the moment above zero, or the net positive moment, required to crack the section:

$$\frac{M_{cr}c_2}{E_c I_g} = \frac{f_r}{E_c} + \frac{P_e}{E_c A_g} \tag{8}$$

Solving:

$$M_{cr}' = \frac{f_r I_g}{c_2} + \frac{P_e I_g}{A_g c_2}$$
(9)

The determination of the cracking moment is further discussed in Refs. 3, 11, 12 and 13.

From distribution line (4) in Fig. 3, corresponding to the total load, and from Fig. 4, Eqs. (10) and (11) are obtained:

$$M_{L2} = M_L - M_{L1} \tag{10}$$

$$\phi_{L2} = M_{L2} / E_c (I'_e)_{L2} \tag{11}$$

where M_{L2} is the total live load moment at the section, M_L , minus M_{L1} in Eq. (5). The effective moment of inertia at a particular section, I'_e , in Eq. (11) is shown in Fig. 4 and computed by Eq. (12). By definition:^{1,2,3,10,11}

$$(I'_{e})_{L2} = \left(\frac{M'_{cr}}{M_{L2}}\right)^{4} I_{g} + \left[1 - \left(\frac{M'_{cr}}{M_{L2}}\right)^{4}\right] I_{cr} \leq I_{g} \quad (12)$$

where M'_{cr} is computed in Eq. (9) and M_{12} in Eq. (10).

From Fig. 4 and Eq. (6):

Total
$$\phi = -\phi'_{p} + \phi'_{D} + \phi_{L1} + \phi_{L2} = \phi_{L2}$$
(13)

and

$$\phi_L = \phi_{L1} + \phi_{L2} \tag{14}$$

Deflection of a Beam

Analogous to the above developments for curvatures, the corresponding deflections are shown in Fig. 5 and computed in the following equations. This figure is presented in terms of KM versus Δ in order that the single line with Slope = $E_c I_g/L^2$ in Fig. 5 can be applied to the deflection under different load distributions (different K's), such as due to prestress, dead load and live load in a typical problem.

Analogous to Eqs. (1) to (4) due to prestress and dead load:

$$\Delta_p' = K_p P_e e_p L^2 / E_c I_g \tag{15}$$

$$\Delta_p = \Delta'_p \left(E_c / E_{ci} \right) \left(P_i / P_e \right) \tag{16}$$

$$\Delta_D' = K_D M_D L^2 / E_c I_g \tag{17}$$

$$\Delta_p = \Delta_p' \left(E_c / E_{ci} \right) \tag{18}$$

Analogous to Eq. (5), and as shown in Fig. 5, for zero deflection:

$$K_L M_{L1} = K_p P_e e_p - K_D M_D \tag{19}$$

and

$$M_{L1} = (K_p/K_L) P_e e_p - (K_D/K_L) M_D (20)$$

Also from Fig. 5:

$$\Delta_{IA} = \Delta'_{p} - \Delta'_{D} \tag{21}$$

In this uncracked region:

$$\Delta_{L1} = K_L M_{L1} L^2 / E_c I_g \tag{22}$$

Eqs. (21) and (22) correspond to Eqs. (6) and (7) for curvatures, respectively.

Analogous to Eqs. (10) and (11), and as shown in Fig. 5, for the total load:

$$K_L M_L = K_L M_{L1} + K_L M_{L2} \tag{23a}$$

$$M_{L2} = M_L - M_{L1}$$
 (23b)

and

$$\Delta_{L2} = K_L M_{L2} L^2 / E_c (I_e)_{L2}$$
(24)

The average effective moment of inertia for a beam, I_e , in Eq. (24) is shown in Fig. 5 and computed by Eq. (25). By definition:^{1,2,3,10,11}

$$(I_e)_{L2} = \left(\frac{M'_{cr}}{M_{L2}}\right)^3 I_g + \left[1 - \left(\frac{M'_{cr}}{M_{L2}}\right)^3\right] I_{cr} \le I_g \qquad (25)$$

where M'_{cr} is computed in Eq. (9) and M_{tr} in Eq. (10).

From Fig. 5 and Eq. (21):

$$\Gamma \text{otal } \Delta = -\Delta_p' + \Delta_D' + \Delta_{L1} + \Delta_{L2} = \Delta_{L2}$$
(26)

and

$$\Delta_L = \Delta_{L1} + \Delta_{L2} \tag{27}$$

In the above equations for computing deflections, the bending moments are usually the maximum moments for simple spans and the maximum moments between inflection points for continuous spans, with the deflection coefficients, K, defined accordingly.

DESIGN EXAMPLE — SIMPLE SPAN PARTIALLY PRESTRESSED SINGLE-T BEAM

Design Details and Stress Analysis

The design conditions, properties, loads and moments are shown in Table 1, and the design details are depicted in Fig. 6. The design is shown to be satisfactory based on the ACI Code allowable stresses for partially prestressed members. $P_i = f_{pi}A_p = (1302 \text{ MN/m}^2) (0.0016 \text{ m}^2)$ = 2.083 MN (468 kips)

$$P_e = f_{pe} A_p = (1042) (0.0016)$$

= 1.667 MN (375 kips)

Concrete stresses at transfer:

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 $\operatorname{End} f_1 = -\frac{P_i}{A_e} + \frac{P_i e_e}{S_1}$ $= -\frac{2.083}{0.3612} + \frac{(2.083)(0.2192)}{0.1117}$ $= -5.77 + 4.09 = -1.68 \text{ MN/m}^2 = -5.77 - 27.42 + 17.00$ = - 1.68 MPa (244 psi) End $f_2 = -\frac{P_i}{A_a} - \frac{P_i e_e}{S_a}$ = -5.77 - (2.083)(0.2192)0.04248 = -5.77 - 10.75= - 16.52 MPa (2396 psi) $\text{Midspan} f_1 = -\frac{P_i}{A_g} + \frac{P_i e_c}{S_1} - \frac{M_D}{S_1}$ $= -5.77 + \frac{(2.083)(0.5592)}{0.1117} - \frac{0.722}{0.1117}$ = -5.77 + 10.43 - 6.46= - 1.80 MPa (261 psi)

Midspan $f_2 = -\frac{P_i}{A_g} - \frac{P_i e_c}{S_2} + \frac{M_D}{S_2}$ $= -5.77 - \frac{(2.083)(0.5592)}{0.04248} + \frac{0.722}{0.04248}$ = -16.19 MPa (2348 psi)

The above stresses are now compared to the following ACI Code allowable stresses:

Compression at transfer $= 0.60 f'_{ci}$ = (0.60) (28)= 16.80 MPa (2437 psi) Tension at transfer = $3\sqrt{f_{ci}}$, psi $= 0.2491 \sqrt{f_{ci}}, MPa$ $= 0.2491 \sqrt{28}$ = 1.32 MPa (191 psi) Table 1. Design conditions, properties, loads and moments for design example.

Material Properties (ACI)

Steam cured normal weight concrete-Unit weight = 2320 kg/m3 x 1.04 to include extra weight of steel = 2410 kg/m^a (150 pcf) $f_{c1}' = 28 \text{ MPa} (4060 \text{ psi}), f_c' = 34 \text{ MPa} (5080 \text{ psi}), f_{pu} = 1860 \text{ MPa} (270 \text{ K})$ $f_{pl} = 0.70 f_{pu} = 1302 \text{ MPa} (189 \text{ ksi}), \text{Assume} f_{pe} = 0.80 f_{pl} = 1042 \text{ MPA} (151 \text{ ksi})$ $f_r = 7.5 \sqrt{f_c^*}, \text{ psi} = 0.6228 \sqrt{f_c^*}, \text{ MPa} = 0.6228 \sqrt{35} = 3.68 \text{ MPa} (534 \text{ psi})$ $E_{ct} = 57,600 \sqrt{f_{c1}}, \text{ psi} = 4783 \sqrt{f_{c1}}, \text{ MPa} = 4783 \sqrt{28} = 25,310 \text{ MPa} (3.67 \ 10^6 \text{ psi})$ $E_c = 4783 \sqrt{f_c} = 4783 \sqrt{35} = 28,300 \text{ MPa} (4.10 \text{ x} 10^6 \text{ psi})$ $E_p = 186,000 \text{ MPa} (27.0 \text{ x } 10^6 \text{ psi for strand}), n = E_p/E_c = 186,000/28,300 = 6.57$ Section Properties $c_2 = 65.92 \text{ cm}, c_1 = 91 - c_2 = 25.08 \text{ cm}$ $e_e = 21.92 \text{ cm}, d = 91 - \text{say } 10 = 81.00, e_e = d - c_1 = 55.92 \text{ cm}$ $A_g = 3612 \text{ cm}^2, I_g = 2,800,200 \text{ cm}^4$ $S_1 = I_g/c_1 = 111,700 \text{ cm}^3, S_2 = I_g/c_2 = 42,480 \text{ cm}^3$ Considering only the rectangular flange in compression (neglecting the taper), $(244) (4) (\alpha_{cr} d - 2) = (6.57) (16) (81.00 - \alpha_{cr} d)$ Solving, $\alpha_{cr} d = 9.68 \text{ cm}$ $I_{cr} = (244) (4)^{9}/12 + (244) (4) (9.68 - 2)^{2} + (6.57) (16) (81.00 - 9.68)^{2} = 593,600 \text{ cm}^{4}$ (USE) (versus correct value of 599,900 cm4) Loads and Moments $w_p = (0.3612 \text{ m}^2) (2410 \text{ kg/m}^3) (0.008907 \text{ kN/kg}) = 8.54 \text{ kN/m} (585 \text{ lb/ft})$ Assume $w_L = 7.5$ kN/m (3.07 kN/m², 514 lb/ft, 64.1 psf) $M_D = w_D L^2/8 = (8.54) (26)^2/8 = 722 \text{ kN-m} (532 \text{ ft-k})$ $M_L = w_L L^2/8 = (7.5) (26)^2/8 = 634 \text{ kN-m} (468 \text{ ft-k})$ Total Gravity Load Moment = M_{p+L} = 1356 kN-m (1000 ft-k)

Hence, the computed stresses at transfer are satisfactory.

Concrete stresses after losses with live load:

$$\begin{aligned} \text{Midspan} f_1 &= -\frac{P_e}{A_g} + \frac{P_e e_c}{S_1} - \frac{M_{D+L}}{S_1} \\ &= -\frac{1.667}{0.3612} + \frac{(1.667) (0.5592)}{0.1117} - \frac{1.356}{0.1117} \\ &= -4.62 + 8.35 - 12.14 \\ &= -8.41 \text{ MPa} (1220 \text{ psi}) \end{aligned}$$

 $\begin{aligned} \text{Midspan} \, f_2 &= -\frac{P_e}{A_g} - \frac{P_e \, e_c}{S_2} + \frac{M_{D+L}}{S_2} \\ &= -4.62 - \frac{(1.667) \, (0.5592)}{0.04248} + \frac{1.356}{0.04248} \\ &= -4.62 - 21.94 + 31.92 \\ &= +5.36 \text{ MPa} \, (777 \text{ psi}) \end{aligned}$

The computed stresses are again compared with the following ACI Code allowable stresses:

Compression after losses:

- $= 0.45 f'_c$
- = (0.45)(35)
- = 15.75 MPa (2284 psi)

Tension after losses:

- $> f_r = 3.68$ MPa (534 psi) (Table 1)
- $< 12 \sqrt{f_c}$, psi
- $< 0.9965 \sqrt{f_c'}$, MPa
- $= 0.9965 \sqrt{35} = 5.90 \text{ MPa} (856 \text{ psi})$

According to the ACI Code, the computed stresses after losses are satisfactory, except that the live load deflection must be computed by a bilinear partially prestressed method (partially cracked section).

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 Table 2. Numerical solution for design example

 (Hand calculations by Newmark numerical procedure¹⁴).

	Midspan									
	-	WL					Multipline			
Description				B	eam		1			Units
L/2 = 13 m										
2	3.25 m 3.25 m				3.25 m 3.25 m					
Section No. 0	1	1		2		3		4		-
<i>e_p</i> 21.	92	30.	42	38.	92	47.	42	55.	92	cm
$a = e_p + c_1 = e_p + 25.08 = 47.$	00	55.	50	64.	00	72.	50	81.	00	cm
L ₋ 193	500	979	20	366	100	8.	85	9.	600	cm om4
	000	212,	500	500,	100	410,	000	000,	000	em
$\phi'_p = P_e e_p / E_e I_p [Eq. (1)] \qquad 0.$	4611	0.	6399	0.	8187	0.	9975	1.	1763	10-3 1/m
ϕ'_p (see Footnote 1) —		2.	080	2.	661	3.	242	3.	629 x	Dimen-
Slope (starting with half	9.798		7.718		5.057		1.815		10.*	Dimen-
Deflection, Δ'_p 0		9.	798	17.	516	22.	573	24.	388	3250 x
Deflection, Δ'_{p} 0		31.	8	56.	9	73.	4	79.	3	10 ⁻³ mm mm
<i>M_p</i> 0		315.	9	541.	5	676.	9	722.	0	kN-m
$\phi'_D = M_D / E_c I_g [Eq. (3)] = 0$		0.	3986	0.	6833	0,	8542	0.	9111	10-3 1/m
$\overline{\phi_D}$ (see Footnote 2)	0	1.	265	2.	190	2.	745	2.	930 x	Dimen-
Slope (starting with half	7.6	7.665		6.400		4.210		1.465		Dimen-
Deflection, Δ_D' 0		7.	665	14.	065	18.	275	19.	740	sionless 3250 x
Deflection A'			0		-	-		~		10 ⁻³ mm
Denection, Δ_D 0	-	24.	9	45.	1	59.	4	64.	2	mm
$M_{L1} = P_e e_p - M_D [Eq. (5)]$ 365.	4	191.	2	107.	3	113.	6	210.	2	kN-m
$\phi_{L1} = M_{L1} / E_c I_g [\text{Eq. (7)}] \qquad 0.$	4611	0.	2413	0.	1354	0.	1433	0.	2653	10-3 1/m
$M_L = M = M (F_C 10) - 265$		277.	4	475.	5	594.	4	634.	0	kN-m
$M_{L2}^{\prime} = M_{L}^{\prime} = M_{L1}^{\prime} [Eq. 10/] = 365.$ M_{-}^{\prime} / M_{re} (see Footnote 3)	4	80.	2	368.	20571	480.	8	423.	8215	KN-m Dimon-
		-	*	0.	5011	0.	1029	0.	0010	sionless
(M'cr/ML2) ⁴		>	1	0.	839	0.	289	0.	478	Dimen-
										sionless
$(I_e^{\prime})_{L2}$ (Eq. 12) 2.	800	2.	800	2.	445	1.	231	1.	648	10 ⁶ cm ⁴
$\phi_{L2} = M_{L2} / E_c (I'_e)_{L2} [Eq. (11)] - 0.$	4611	0.	1088	0,	5321	1.	3801	0.	9087	10-3 1/m
$ \phi_L = \phi_{L1} + \phi_{L2} [\text{Eq. (14)}] 0. $	0000	0.	3501	0.	6675	1.	5234	1.	1740	10-3 1/m
φ_L (see Pootnote 2) —		1.	129	2.	315	4.	625	4.	005 x	Dimen-
Slope (starting with half	10.0	10.072		8.943		6.628		2.003		Dimen-
Deflection, Δ_L 0.		10.	072	19.	015	25.	643	27.	646	3250 x
Deflection, Δ_L 0		32.	7	61.	8	83.	3	89.	9	10 ⁻³ mm

See notes on opposite page.

Uncracked Beam Deflection Computed by Numerical Integration of Elastic Curvatures (M/EI_a). Cracked beam deflection computed by numerical integration of curvatures using I' (with 4th power equation) Fig. 4

The following sample calculations pertain to Section 4 in Table 2: $\alpha_{ar} d = 9.68 \text{ cm} (3.81 \text{ in.})$ (Calculation shown in Table 1)

 $I_{cr} = 593,600 \text{ cm}^4 (14,260 \text{ in.}^4)$ (Calculation shown in Table 1)

$$\begin{split} \phi_p' &= P_e \, e_p / E_c \, I_g & \text{Eq. (1)} \\ &= \frac{(1.667) \, (0.5592)}{(28,300) \, (0.028002)} \\ &= 1.1763 \, \text{x} \, 10^{-3} \, 1/\text{m} \\ &= (0.359 \, \text{x} \, 10^{-3} \, 1/\text{ft}) \end{split}$$

As shown in Footnote 1 of Table 2:

$$\overline{\phi_p}' = \frac{3.25}{6}$$

 $(0.9975 + 4 \times 1.1763 + 0.9975)10^{-3}$ $= 3.629 \times 10^{-3}$ (dimensionless)

From Table 2:

Midspan $\Delta'_{p} = 79.3 \text{ mm} (3.13 \text{ in.})$ which is exactly the same as the result by the direct calculation method (next section). The reason for this is shown in Footnote 1 of Table 2.

 $M_p = 722 \text{ kN-m} (532 \text{ ft-k})$ (calculation shown in Table 1) Eq. (3) $\phi_n' = M_n / E_c I_o$

0.722 (28,300) (0.028002) $= 0.9111 \text{ x } 10^{-3} \text{ 1/m} (0.278 \text{ x } 10^{-3} \text{ 1/ft})$

As shown in Footnote 2 of Table 2:

$$\overline{\phi_{D}'} = \frac{3.25}{12}$$
(0.8542 + 10 x 0.9111 + 0.8542)10⁻³

$$= 2.930 \text{ x } 10^{-3} \text{ (dimensionless)}$$

From Table 2:

Midspan $\Delta'_{p} = 64.2 \text{ mm} (2.53 \text{ in.})$

which is exactly the same as the result by the direct calculation method (next section). The reason for this is shown in Footnote 2 of Table 2.

$$\begin{split} M_{L1} &= P_e e_p - M_B & \text{Eq. (5)} \\ &= \langle 1667 \rangle (0.5592) - 722 \\ &= 210.2 \text{ kN-m } (155 \text{ ft-k}) \\ \phi_{L1} &= M_{L1} / E_c I_g & \text{Eq. (7)} \\ &= \frac{0.2102}{(28,300) (0.028002)} \\ &= 0.2653 \text{ x } 10^{-3} \text{ 1/m} \\ (0.0809 \text{ x } 10^{-3} \text{ 1/ft}) \\ M_{c\,r}' &= \frac{f_r I_g}{c_2} + \frac{P_e I_g}{A_g c_2} & \text{Eq. (9)} \\ &= \frac{(3.68) (0.028002)}{0.6592} + \frac{(1.667) (0.028002)}{(0.3612) (0.6592)} \end{split}$$

$$\begin{split} M_{L2} &= M_L - M_{L1} & \text{Eq. (10)} \\ &= 634.0 - 210.2 \\ &= 423.8 \text{ kN-m (313 ft-k)} \end{split}$$

$$(M'_{cr}/M_{L2})^4 = (352.4/423.8)^4$$

= 0.8315⁴ = 0.478

$$\begin{split} \langle I_e' \rangle_{L2} &= \left(\frac{M_{c\,r}'}{M_{L2}}\right)^4 I_g + \qquad \text{Eq. (12)} \\ & \left[1 - \left(\frac{M_{c\,r}'}{M_{L2}}\right)^4 \right] I_{cr} \leqslant I_g \end{split}$$

$$= (0.478) (2,800,200) + (1 - 0.478) (593,600) = 1,648,400 \text{ cm}^4 (39,600 \text{ in.}^4)$$

From Newmark numerical procedure¹⁴ with incremental length = L/8:

$$\overline{\phi_1} = \frac{L/8}{6} \left(\phi_0 + 4 \phi_1 + \phi_2 \right), \ \overline{\phi_2} = \frac{L/8}{6} \left(\phi_1 + 4 \phi_2 + \phi_3 \right), \text{ etc.}$$

2. For 2nd degree parabolic curvature (M/EI) diagrams (the dead load case in the example), the following $\overline{\phi_1} = \frac{L/8}{12} (\phi_0 + 10 \phi_1 + \phi_2), \ \overline{\phi_2} = \frac{L/8}{12} (\phi_1 + 10 \phi_2 + \phi_3), \ \text{etc.}$ is exact:

For most other cases, the equation is very accurate but not exact (the live load case in the example).

3. Beam is uncracked at the end (at the top under the negative moment). Use Ig at the end section.

^{1.} For straight line curvature (M/EI) diagrams (the prestress case in the example), the following is exact:

$$\begin{split} \phi_{L2} &= M_{L2} / E_c \, (I_e^{*})_{L2} & \text{Eq. (11)} \\ &= \frac{0.4238}{(28,300) \, (0.016484)} \\ &= 0.9087 \, \text{x} \, 10^{-3} \, 1/\text{m} \, (0.277 \, \text{x} \, 10^{-3} \, 1/\text{ft}) \\ \phi_L &= \phi_{L1} + \phi_{L2} & \text{Eq. (14)} \\ &= (0.2652 \, 1.0 \, 00057) 10^{-3} \end{split}$$

 $= (0.2653 + 0.9087)10^{-3}$ = 1.1740 x 10⁻³ 1/m (0.358 x 10⁻³ 1/ft)

As shown in Footnote 2 of Table 2:

$$\overline{\phi_L} = \frac{3.25}{12}$$
(1.5234 + 10 x 1.1740 + 1.5234)10⁻³

= 4.005×10^{-3} (dimensionless)

From Table 2:

Midspan $\Delta_L = 89.9 \text{ mm} (3.54 \text{ in.})$ versus 89.1 mm (3.51 in.) by the direct calculation method in the next section. These results demonstrate the typical close agreement (see Refs. 1 and 3) between the two procedures for uniformly distributed live loading (and similar but to a lesser degree for two or more point loads per span) — using the fourth power equation for I'_e when computing curvatures first and then numerically solving for the deflections, and using the third power equation for I_e when computing deflections directly.

Direct Calculation of Uncracked Beam Deflection. Cracked beam deflection computed directly using the average I_e (with 3rd power equation) Fig. 5

Ν

$$\begin{split} \Delta_p' &= K_p P_e \, e_p \, L^2 / E_c \, I_g, e_p = e_c & \text{Eq. (15)} \\ &= \frac{P_e \, (e_c - e_e) L^2}{12 \, E_c \, I_g} + \frac{P_e \, e_e \, L^2}{8 \, E_c \, I_g} & \text{Ref. (3)} \\ &= \frac{(1.667) \, (0.5592 - 0.2192) \, (26)^2}{(12) \, (28,300) \, (0.028002)} & + \\ &\frac{(1.667) \, (0.2192) \, (26)^2}{(8) \, (28,300) \, (0.028002)} \end{split}$$

= 0.0793 m = 79.3 mm (3.12 in.)

which is exactly the same as the result by the numerical integration method in the previous section. The reason for this is shown in Footnote 1 of Table 2. Solving Eq. (15) above, $K_p = 0.0997$.

For uniformly distributed loading: $K_D = K_L = 5/48 = 0.1042$

Checking the conditions of Fig. 5: $K_p P_e e_p = (0.0997) (1.667) (0.5592)$ = 0.0929 MN-m = 92.9 kN-m(69 ft-k) $> K_p M_p = (5/48) (722)$ = 75.2 kN-m (55 ft-k)

$$\begin{array}{l} \Delta_p = \Delta'_p \ (E_c/E_{ci}) \ (P_i/P_e) & \text{Eq. (16)} \\ = (79.3) \ (28,300/25,310) \ (2.083/1.667) \\ = 111 \ \text{mm} \ (4.37 \ \text{in.}) \end{array}$$

$$= 0.0642 \text{ m} = 64.2 \text{ mm} (2.53 \text{ in.})$$

which is exactly the same as the result by the numerical integration method in the previous section. The reason for this is shown in Footnote 2 of Table 2.

$$\begin{array}{l} \Delta_D = \Delta_D' \; (E_c / E_{ct}) & \text{Eq. (18)} \\ = \; (64.2) \; (28,300/25,310) \\ = \; 71.8 \; \text{mm} \; (2.83 \; \text{in.}) \end{array}$$

$$\begin{split} A_{L1} &= \langle K_p / K_L \rangle P_e e_p - \langle K_p / K_L \rangle M_p, e_p = e_c \\ &= \frac{0.0997}{0.1042} (1.667) (0.5592) \\ &- (1.000) (0.722) \qquad \text{Eq.} (20) \end{split}$$

$$= 0.170 \text{ MN-m} = 170 \text{ kN-m} (125 \text{ ft-k})$$

$$\Delta_{L1} = K_L M_{L1} L^2 / E_c I_g \qquad \text{Eq. (22)} (5/48) (0.170) (26)^2$$

$$= 0.0151 \text{ m} = 15.1 \text{ mm} (0.59 \text{ in.})$$

$$M_{L2} = M_L - M_{L1}$$
 Eq. (23)
= 634 - 170
= 464 kN-m (342 ft-k)

 $M'_{cr} = 352.4 \text{ kN-m} (260 \text{ ft-k})$ (calculated in previous section)

$$(I_e)_{L2} = \left(\frac{M'_{cr}}{M_{L2}}\right)^3 I_g + \left[1 - \left(\frac{M'_{cr}}{M_{L2}}\right)^3\right] I_{cr} \le I_g \text{ Eq. (25)}$$
$$= (0.438) (2.800, 200) + (25)$$

(1 - 0.438) (593,600) = 1,560,100 cm⁴ (37,480 in.⁴)

$$\begin{split} \Delta_{L2} &= K_L M_{L2} L^2 / E_c \ (I_e)_{L2} & \text{Eq. (24)} \\ &= \frac{(5/48) \ (0.464) \ (26)^2}{(28,300) \ (0.015601)} \\ &= 0.0740 \text{ m} \\ &= 74.0 \text{ mm} \ (2.91 \text{ in.}) \\ \Delta_L &= \Delta_{L1} + \Delta_{L2} & \text{Eq. (27)} \\ &= 15.1 + 74.0 \\ &= 89.1 \text{ mm} \ (3.51 \text{ in.}) \end{split}$$

versus 89.9 mm (3.54 in.) by the numerical integration method in the previous section. These results demonstrate the typical close agreement (see Refs. 1 and 3) between the two procedures for uniformly distributed live loading (and similar but to a lesser degree for two or more point loads per span), using the third power equation for I_e when computing deflections directly, and using the fourth power equation for I'_e when computing curvatures first and then numerically solving for the deflections.

The ACI Code allowable deflections for roofs and floors under live load are:

Roofs: L/180 = 26,000/180= 144 mm (5.67 in.)

Floors: L/360 = 72 mm (2.83 in.)

Based on these limits, the design is satisfactory for roofs but not for floors (Computed $\Delta_L = 89$ mm and 90 mm by the two methods).

CONCLUDING REMARKS

Unified *I*-effective procedures for partially cracked non-prestressed and prestressed member curvatures and deflections have been summarized. The analytical and experimental development of these procedures is described in Refs. 10 and 11. Both of the procedures empirically account for the effect of tension stiffening.

In this paper the application of the unified procedures is illustrated for a typical single-T beam designed as a partially prestressed member in accordance with the ACI Code, which requires that deflections be computed. The midspan live load deflection is computed as 89.9 mm (3.54 in.) by the numerical integration of curvatures, and 89.1 mm (3.51 in.) by direct calculation.

This demonstrates the typical close (although not always that close) agreement between the two procedures for uniformly distributed loading using the third power equation for I_e when computing deflections directly, and using the fourth power equation for I'_e when computing curvatures first and then numerically solving for the deflections. Such results are consistent with previous results,^{1,3} particularly those of Ref. 1 for non-prestressed members in which the two equations were initially determined empirically.

The design example, analyzed by these methods, is shown to be satisfactory for roofs but not for floors, according to the ACI Code allowable live load deflections.

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APPENDIX—NOTATION

- A_g = area of gross section, neglecting the steel
- A_p = area of prestressing steel
- c₁, c₂ = distance from uncracked centroid (gross section) to top, bottom surfaces, respectively
- d = effective depth of a beam (distance from compression face to center of steel)
- E_c = modulus of elasticity of concrete at the time the superimposed loading, such as live load, is applied; normally taken to be at age 28 days
- E_{et} = modulus of elasticity of concrete at the time of initial loading, such as at the time of prestress transfer
- E_p = modulus of elasticity of prestressing steel
- $e_c, e_e =$ eccentricity at midspan, end of a beam, respectively
- e_p = eccentricity of prestressing steel
- f_1, f_2 = flexural stress in concrete at top, bottom surfaces, respectively
- f_{pe} = stress in prestressing steel corresponding to the effective prestress force, P_e , after all losses
- f_{pi} = temporary stress in prestressing steel at transfer (initial prestress)
- f_{pu} = ultimate tensile strength of prestressing steel
- $f_r =$ modulus of rupture of concrete
- f'_c = compressive strength of concrete, normally at age 28 days
- $f_{ct}' =$ compressive strength of concrete at the time of prestress transfer
- Icr = moment of inertia of the fully cracked section
- I_e = effective moment of inertia for deflection
- I'_e = effective moment of inertia for curvature
- $(I'_e)_{L2}, (I_e)_{L2} =$ effective moment of inertia for curvature and deflection, respectively, for the part of the live load moment, M_{L2} , corresponding to a positive curvature (concave upward), deflection (downward)

- I_g = moment of inertia of gross section, neglecting the steel
- I_{ucr} = moment of inertia of uncracked transformed section
- K_D , K_L , K_p = deflection coefficient for dead load moment, live load moment, prestress moment, respectively
- L = span length
- $M_{bv} = \text{total bending moment due to}$ prestress
- M_{bv}^{o} = statically determinate moment due to prestress = $P_{e} e_{p}$
- M_{bv} = statically indeterminate moment due to prestress
- M_{cr} = cracking moment (moment above zero, or the net positive moment, necessary to crack a beam), as defined by Eq. (9)
- M_D , M_L = dead load moment, live load moment, respectively
- M_{L1} = part of live load moment corresponding to zero curvature, deflection
- M_{L2} = part of live load moment corresponding to positive curvature (concave upward), deflection (downward)
- n = modular ratio
- $P_e = effective prestress force (after losses)$
- P_t = initial prestress force, or prestress force at transfer
- S_1 , S_2 = section moduli of top, bottom surfaces, respectively
- w_D , w_L = uniformly distributed dead load, live load, respectively
- α = ratio of distance from centroid to top surface to *d*
- $\alpha_{cr} d = \text{location of fully cracked centroid}$
- $\alpha_e d = \text{location of partially cracked cen$ $troid}$
- $\alpha_g d = \text{location of uncracked (gross sec$ $tion) centroid}$

 $\Delta = deflection$

- ϕ = curvature
- Δ_D , ϕ_D = deflection, curvature due to dead load
- Δ'_{D} , ϕ'_{D} = fictitious deflection, curvature

due to dead load using E_c (rather than E_{ci}) in the calculation

- $\Delta_L, \phi_L = \text{deflection, curvature due to live load}$
- $\Delta_{L1}, \phi_{L1} = \text{part of the live load deflection},$ curvature which, together with the prestress camber, produces zero deflection, curvature
- $\Delta_{L2}, \phi_{L2} =$ part of the live load deflection, curvature corresponding to posit-

ive values (downward deflection, concave upward curvature); also the netor total deflection, curvature

- $\Delta_p, \phi_p = \text{deflection, curvature due to pre$ $stress}$
- $\Delta'_{p} \phi'_{p}$ = fictitious deflection, curvature due to prestress using E_{c} (rather than E_{ci}) in the calculation
- $\overline{\phi}$ = equivalent concentrated angle change in Newmark procedure

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